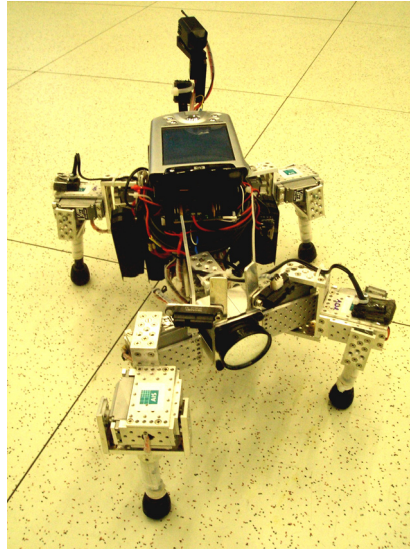


AMOS-WD02



Developer Manoonpong, Poramate and Pasemann, Frank
Fraunhofer Institut Autonome Intelligente Systeme (AIS), Germany
poramate.manoonpong, frank.pasemann@ais.fraunhofer.de
www.ais.fraunhofer.de/INDY/

Points of interest - Reactive behavior, e.g. sound tropism and obstacle avoidance behavior
- Demonstration platform for evolved modular neural control

Technical details

Type of machine	4-legged walking machine with a backbone joint for faster walking and an active tail
Size & weight	L: 28cm x W: 30cm x H: 14cm; 3.3kg
Preferred substrate	flat area with a corner and some obstacles